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a power source and has a control device for selecting forward or reverse directions of movement. The method includes utilizing a control lever for moving the stabilizer leg between fully extended and fully retracted positions. The control lever is normally located in and biased to a neutral position. Next, manually moving the control lever to either of an extend position or a retract position. Then, manually holding the control lever in either of the extend or retract positions to respectively extend or retract the stabilizer leg to any of a plurality of desired positions between the fully extended and fully retracted positions. Next, manually moving the control lever to an auto-retract position. Finally, retaining the control lever in the auto-retract position without further manual manipulation thereof through a responsive means that overcomes the biasing action of the control lever to facilitate the automatic retraction of the stabilizer leg from any of the plurality of desired positions to the fully retracted position.

Please amend the last paragraph of Page 4 (lines 9-35) of the Specification, as follows:

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In yet another aspect of the present invention, a method is disclosed for automatically retracting a stabilizer leg for a work machine. The work machine is operatively associated with a power source and has a control device for selecting forward or reverse directions of movement for the work machine. The method comprises the steps of utilizing a pair of control levers for moving a pair of stabilizer legs between fully extended and fully retracted positions. The control levers are normally located in a neutral position and movable to first, second, and third positions. The movement of either of the control levers to the first position promotes the movement of a respective stabilizer leg to a plurality of